

GIVI MISURE s.r.l.

Via Assunta 57 - 20054 NOVA MILANESE (MI) ITALY

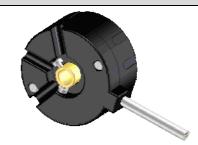
Droject	Dalagga		Title
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Code	Project	Release	Title
ST10	A04	\boldsymbol{A}	TECHNICAL DATASHEET

OPTICAL ENCODER EN413

GENERAL FEATURES

- Optical rotary encoder of small overall dimensions.
- Bi-directional signals with zero pulse.
- Up to 500 pulses per revolution.
- High rotational accuracy.
- Flange and cover made of zama.
- Cable output in radial position.



MECHANICAL AND ELECTRICAL FEATURES

CABLES AND ELECTRICAL CONNECTIONS

Cable 9 cores Ø = 4.1 mm, PVC external sheath

Wires section:

- for power supply: 0.08 mm²

0.08 mm² - for signals:

Cable 5cores Ø = 4.1 mm, PVC external sheath

Wires section:

- for power supply: $0.35\ mm^2$ - for signals: 0.14 mm²

Do not exceed the minimum cable bending radius of 30 mm.

LINE D	RIVER	PUSH-PULL		WIRE COLOUR	
WITH ZERO	WITHOUT ZERO	WITH ZERO	WITHOUT ZERO	WIRE COLOUR	
Α	А	В	В	Green	
Ā	Ā	NC	NC	Orange	
В	В	А	А	White	
B	ΙB	NC	NC	Light blue	
Z	Z	Z	NC	Brown	
Z	NC	NC	NC	Yellow	
SCH	SCH	SCH	SCH	Shield	
VS = 5V	VS = 5V	VS = 5V	VS = 5V	Red	
VS0 = 0V	VS0 = 0V	VS0 = 0V	VS0 = 0V	Blue	
9 CORES		5 CC	RES	CABLE	

Code EN413			
Pulses	50 ÷ 500 ppr		
Max. rotation speed	6000 rpm		
Shaft (diameter hole A)	Ø 6 mm (standard)	Ø 6.35 mm (special)	
Protection class	IP 40		
Operating temperature	0 ÷ 70°C		
Storage temperature	-20 ÷ 80°C		
Relative humidity	20 ÷ 90% (not condensed)		
Power supply	5 Vdc ± 5% or	12 ÷ 24 Vdc ± 5%	
Current consumption	45 mA		
Max. frequency	50 kHz		
Output	LINE DRIVER	PUSH-PULL	
Standard cable length	1 m		
Electrical connections	see the rel. table		
Weight	≈ 110 g		

ORDERING CODE

MODEL TYPE PPR POWER SUPPLY SHAFT Ø CABLE OUTPUT CONN. **EN413 BZR** 00100 **D06** M01 PP С 1224

> B0R = bidirectional without zero

00050 = 50 ppr **00100** = 100 ppr

05V = 5V **1224** = 12÷24V

D06 = Ø6mm $635 = \emptyset6.35$ mm

Mxx = cable length in metres **M0.5** = 0.5m

L5 = LINE DRIVER PP = PUSH-PULL

BZR = bidirectional **00500** = 500 ppr with zero

M01 = 1m $\mathbf{M40} = 40 \mathrm{m}_{\mathrm{MAX}}$

Example OPTICAL ENCODER EN413 BZR 00100 1224 D06M01 PPC



A04

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ST10

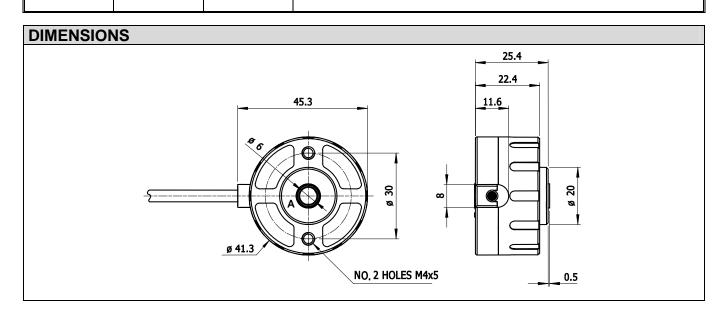
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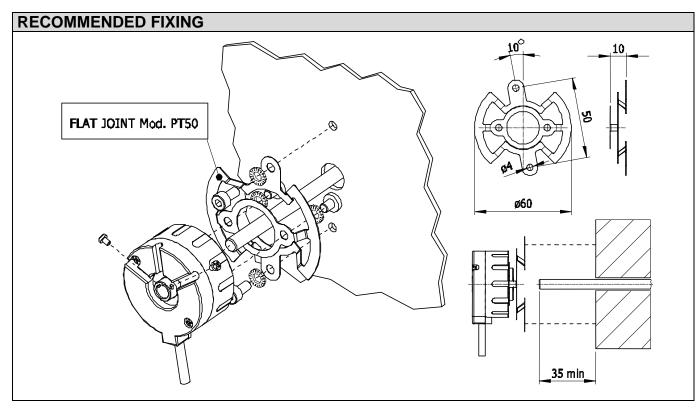
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WHAT TO AVOID

- Any type of mechanical working (cut, drill, mill, etc.)
- Any modification either on the body or on the shaft of the encoder
- Any kind of bad usage
- External hits or stresses

